

# ANALOG Communication

V. CHANDRA SEKAR

*Professor and Head*

*Department of Electronics and Communication Engineering  
SASTRA University, Kumbakonam*

**OXFORD**  
UNIVERSITY PRESS

# Contents

<i>Preface</i>	v
<b>1. Introduction</b>	<b>1</b>
1.1 What is Communication?	1
1.2 Modulation and its Types	1
1.2.1 Need for Modulation	2
1.2.2 Frequency Translation	2
1.2.3 Types of Modulation	2
1.3 Transmitter	3
1.4 Receiver	3
1.5 Digital Communication System	4
1.6 Multiplexing of Signals	5
1.6.1 Frequency Division Multiplexing	5
1.6.2 Time Division Multiplexing	5
<b>2. Signals: An Introduction</b>	<b>6</b>
2.1 Basic Concepts	6
2.2 Classification of Signals	7
2.2.1 Continuous and Discrete Time Signals	7
2.2.2 Periodic and Non-periodic Signals	8
2.2.3 Causal and Non-causal Signals	8
2.2.4 Even and Odd Signals	8
2.2.5 Deterministic and Random Signals	9
2.2.6 Real and Complex Signals	10
2.2.7 Energy-Type and Power-Type Signals	10
2.3 Typical Signals and Their Properties	11
2.3.1 Sinusoidal Signal	11
2.3.2 Complex Exponential Signal	11
2.3.3 Unit-Step Signal	12
2.3.4 Rectangular Pulse	12
2.3.5 Triangular Signal	13
2.3.6 The Sinc Signal	13
2.3.7 Sign or Signum Signal	13
2.3.8 Impulse or Delta Signal	14
2.3.9 Singular Function	16
2.3.10 Shifting, Inversion, Scaling, and Convolution of Signal	16
2.4 Classification of Systems	17
2.4.1 Discrete Time and Continuous Time Systems	18
2.4.2 Linear and Non-linear Systems	18
2.4.3 Time Invariant and Time Varying Systems	18
2.4.4 Causal and Non-causal Systems	19

**x Contents**

2.4.5	Instantaneous and Dynamic Systems	20
2.4.6	Stable and Unstable Systems	20
2.5	Delta Function and Convolution	20
2.5.1	Delta Function	20
2.5.2	Convolution	22
2.6	Fourier Series and Transform	24
2.6.1	Fourier Series	24
2.6.2	Fourier Transform	29
2.7	Laplace Transform	32
2.8	The $z$ -Transform	36
2.9	Signal Energy and Energy Spectral Density	39
2.10	Energy Spectral Density	41
2.11	Essential Bandwidth of a Signal	42
2.12	Energy of Modulated Signal	42
2.13	Signal Power and Power Spectral Density	43
2.13.1	Power Spectral Density (PSD)	44
<b>3.</b>	<b>Amplitude Modulation</b>	<b>58</b>
3.1	Baseband Communication	58
3.2	Theory of AM	59
3.3	Frequency Spectrum of Sinusoidal AM	60
3.4	Amplitude Modulation Index	62
3.5	Average Power for Sinusoidal AM	64
3.6	Modulation by Several Sine Waves	66
3.7	Double Sideband Suppressed Carrier (DSBSC)	67
3.8	Single Sideband (SSB) Systems	68
3.8.1	Single Sideband with Carrier	68
3.8.2	Single Sideband with Suppressed Carrier	71
3.8.3	Single Sideband with Reduced Carrier	71
3.9	Independent Sideband Amplitude Modulation	72
3.10	Comparison of SSB and AM	72
3.11	Single Sideband: Advantages and Disadvantages	74
3.12	Single Sideband Generation	75
3.13	Vestigial Sideband (VSB) Transmission and Quadrature Amplitude Modulation (QAM)	76
3.13.1	Vestigial Sideband Transmission	76
3.13.2	Quadrature Amplitude Modulation (QAM)	78
3.14	AM Modulators	78
3.14.1	Square Law Modulation (Power Law Modulation)	79
3.14.2	Switching Modulator	80
3.14.3	Transistor Modulators	81
3.14.4	Balanced Modulators	86
3.15	SSB Generation	94
3.15.1	The Filter Method	94
3.15.2	The Phase Shift Method	98
3.15.3	The Third Method	98

3.16	Independent Sideband Transmitter	101
3.17	AM Demodulators	102
3.17.1	Rectifier Detector	102
3.17.2	Envelope Detector	103
3.17.3	Detector Distortion	105
3.17.4	Diagonal Peak Clipping	106
3.17.5	Negative Peak Clipping	108
3.18	SSB Reception	109
3.18.1	Coherent Detection	109
3.18.2	SSB Reception with Pilot Carrier	109
3.19	Demodulation of VSB Signals	110
3.20	Detection of ISB Signals	110
3.21	Transmitters	110
3.21.1	AM Transmitters	111
3.21.2	SSB Transmitters	113
3.22	Trapezoidal Patterns	113
3.23	Receivers	115
3.23.1	AM Receivers	115
3.23.2	SSB Receiver with Pilot Carrier	120
3.23.3	Communication Receivers	120
3.23.4	Receiver Parameters	120
3.24	Automatic Gain and Volume Control Circuits	123
3.24.1	Automatic Gain Control (AGC)	123
3.24.2	Automatic Volume Control (AVC)	126
3.24.3	Squelch Circuit	127
3.25	Comparison and Applications of Various AM Systems	128
3.26	Frequency Translation	129
3.27	Costas Loop	129
3.27.1	Carrier Recovery	129
3.27.2	Digital Implementation	130
3.27.3	Traditional Design Method	131
3.27.4	Detailed Description	132
3.27.5	Costas Versus Conventional Loop	134
3.27.6	Design Considerations for Costas Loop	137
3.27.7	Analysis of a Costas Loop for a Typical Received Signal	138
	<i>Case Study: Software Defined Radio (SDR)</i>	154

#### 4. Angle Modulation

164

4.1	Introduction	164
4.2	Instantaneous Frequency	165
4.3	FM and PM Signals	166
4.3.1	Spectrum of an FM Signal	167
4.3.2	Concept of Angle Modulation	168
4.4	Modulation Index	170
4.4.1	Deviation Sensitivity	170
4.4.2	Frequency Deviation	172
4.4.3	Percentage Modulation	174
4.5	Bandwidth Requirements for Angle Modulated Waves	174

**xii** Contents

4.6	Sinusoidal FM: Narrowband and Wideband	175
4.6.1	Narrowband FM	175
4.6.2	Wideband FM	178
4.7	Spectral Characteristic of a Sinusoidal Modulated FM Signal	181
4.7.1	Spectrum of Constant Bandwidth FM	182
4.8	Average Power in Sinusoidal FM	183
4.9	Deviation Ratio for Non-sinusoidal Frequency Modulation	184
4.10	Phase Modulation	184
4.10.1	Sinusoidal Phase Modulation	185
4.10.2	Digital Phase Modulation	186
4.11	Comparison of FM and PM	186
4.12	FM Generation	187
4.12.1	Direct Method	188
4.12.2	Indirect Method	196
4.13	Phase Modulators	197
4.13.1	Varactor Diode Direct PM Modulators	197
4.13.2	PM Modulator: Direct Method with Transistor	198
4.14	FM Detectors	198
4.14.1	Bandpass Limiter	199
4.14.2	Practical Frequency Demodulators	201
4.14.3	Slope Detector	202
4.14.4	Balanced Slope Detector	203
4.14.5	Foster–Seeley Discriminator	204
4.14.6	Ratio Detector	206
4.14.7	FM Demodulator Using a PLL	207
4.14.8	Practical PLL Circuit	208
4.14.9	Quadrature Detectors	209
4.14.10	Zero Crossing Detector	210
4.14.11	Bias Distortion in FM Demodulation Using Zero Crossing Detectors	212
4.14.12	Amplitude Limiters	212
4.15	FM Transmitters and Receivers	214
4.15.1	Direct FM Transmitters	214
4.15.2	Indirect FM Transmitters	216
4.15.3	FM Stereo Broadcasting	218
4.15.4	FM in TV Broadcasting	219
4.15.5	FM Receivers	219
4.15.6	Single-Chip FM Radio Circuit	222
4.15.7	Capture Effect	223
4.16	Phase Locked Loop (PLL)	224
4.16.1	PLL Basics	225
4.16.2	PLL Operation	225
4.16.3	Lock and Capture Ranges	226
4.16.4	Mathematical Analysis of PLL	227
4.16.5	Linear Analysis of PLL	228
4.16.6	Standard Non-linear Model	229
4.16.7	Digital PLL	229

4.16.8	Software PLLs	231
4.16.9	Phase Comparator	231
4.16.10	Voltage-Controlled Oscillators (VCOs)	236
4.16.11	Loop Filter	236
4.16.12	Applications of PLL	237
4.17	Direct Digital Synthesis (DDS)	238
4.17.1	Basic Concept	238
4.17.2	Need for Direct Digital Synthesis	240
4.17.3	DDS Application in Function Generator Design: A Case Study	241
4.17.4	PLL Frequency Synthesizer: A Case Study	245
4.18	Comparison of Angle Modulation with Amplitude Modulation	249
<b>5.</b>	<b>Pulse Modulation</b>	<b>265</b>
5.1	Introduction	265
5.2	Sampling Theorem	267
5.2.1	Occurrence of Aliasing Error	268
5.2.2	Mathematical Proof of Sampling Theorem	270
5.3	Pulse Amplitude Modulation (PAM)	274
5.3.1	Channel Bandwidth for PAM	274
5.3.2	Natural Sampling	275
5.3.3	Flat Top Sampling	277
5.3.4	Pulse Amplitude Modulation and Time Division Multiplexing (TDM)	279
5.3.5	Signal Recovery	280
5.4	Pulse Width Modulation (PWM)	283
5.4.1	Uses of PWM	283
5.4.2	Why the PWM Frequency is Important	285
5.5	Pulse Position Modulation (PPM)	285
5.6	Generation of PAM	285
5.7	Generation of PWM	286
5.8	Generation of PPM	286
5.9	Pulse Code Modulation (PCM)	287
5.9.1	PCM Basics	288
5.10	PCM Transmitter and Receiver	289
5.10.1	Quantization	289
5.11	Delta Modulation	290
5.11.1	Principle	291
5.11.2	Adaptive DM	293
5.11.3	Differential Pulse Code Modulation (DPCM)	294
5.11.4	Quantization of Signals	294
5.11.5	Quantization Error	296
5.12	Noise Consideration in PCM System	297
5.13	FDM and TDM	298
5.14	Frequency Division Multiplexing Transmitter	299
5.14.1	Frequency Division Multiplexing Receiver	299
5.15	Analog Carrier System	301
5.16	Time Division Multiplexing (TDM)	302
5.17	Synchronous Time Division Multiplexing Transmitter	304

5.18 Synchronous Time Division Multiplexing Receiver 304  
5.19 TDM Digital Carrier System 305

**6. Noise**

**316**

6.1 Introduction 316  
6.2 External Noise 317  
    6.2.1 Atmospheric Noise 317  
    6.2.2 Extraterrestrial Noise 318  
    6.2.3 Industrial Noise (Man-made Noise) 318  
6.3 Internal Noise 319  
    6.3.1 Thermal Noise (Johnson Noise) 319  
    6.3.2 Noise Voltage 320  
    6.3.3 Equivalent Sources for Thermal Noise 321  
    6.3.4 Noise Voltage for Resistors Connected in Series 321  
    6.3.5 Resistors in Parallel 322  
    6.3.6 Thermal Noise Power in a Reactance Circuit 322  
    6.3.7 Spectral Densities 323  
    6.3.8 Power Spectral Response 323  
    6.3.9 Noise Equivalent Bandwidth 324  
    6.3.10 Shot Noise 328  
    6.3.11 Partition Noise 328  
    6.3.12 Flicker Noise 328  
    6.3.13 Burst Noise 329  
    6.3.14 Transit Time Noise 329  
    6.3.15 Avalanche Noise 329  
    6.3.16 Transistor Noise 329  
6.4 Signal-to-Noise Ratio 330  
    6.4.1 Signal-to-Noise Ratio of a Cascaded System 330  
6.5 Noise Figure 332  
    6.5.1 Input Noise of Amplifier in Terms of  $F$  334  
    6.5.2 Noise Factor of Amplifiers in Cascade 334  
6.6 Noise Temperature 335  
6.7 Measurement of Noise Factor and Noise Temperature 336  
6.8 Noise in a Bandpass System 337  
6.9 Noise in AM Systems 338  
    6.9.1 Signal-to-Noise Ratio for SSB 342  
    6.9.2 Single Sideband Companding 343  
6.10 Effect of Noise on Angle Modulation 343  
6.11 Pre-emphasis and De-emphasis Circuits 351  
6.12 Threshold Effect in Angle Modulation 354  
6.13 Mathematical Representation of Noise 356  
    6.13.1 Frequency Domain Representation of Noise 356  
    6.13.2 Spectral Component of Noise 357  
    6.13.3 Superposition of Noise 359  
    6.13.4 Mixing Noise with Sinusoid 359  
    6.13.5 Mixing Noise with Noise 360  
    6.13.6 Linear Filtering of Noise 361

6.13.7	Quadrature Component of Noise	362
6.13.8	Representation of Noise Using Orthogonal Representation	362
6.14	Narrowband Noise	363
6.14.1	Representation of Narrowband Noise in Terms of In-Phase and Quadrature Components	364
6.14.2	Representation of Narrowband Noise in Terms of Envelope and Phase Components	366
6.14.3	Sine Wave Plus Narrowband Noise	368
6.15	Frequency Modulation Feedback (FMFB) Technique	371
<b>7.</b>	<b>Introduction to Digital Communication</b>	<b>385</b>
7.1	Introduction	385
7.2	Digital Amplitude Modulation	387
7.3	<i>I/Q</i> Modulation	388
7.3.1	The Concept of <i>I</i> and <i>Q</i> Channels	389
7.3.2	Application of <i>I/Q</i> Modulation	390
7.3.3	Need for Using <i>I</i> and <i>Q</i>	391
7.4	Some Important Terms	391
7.4.1	Information Capacity, Bits, and Bit Rate	391
7.4.2	M-ary Encoding	392
7.4.3	Baud and Minimum Bandwidth	392
7.5	Frequency Shift Keying	393
7.5.1	FSK Baud and Bandwidth	394
7.6	Phase Shift Keying	396
7.6.1	Binary Phase Shift Keying	396
7.6.2	M-ary Phase Shift Keying (MPSK)	399
7.6.3	Quadrature Phase Shift Keying (QPSK)	400
7.6.4	PSK Modulation	404
7.6.5	Modulation Index of a QPSK signal	405
7.6.6	Offset QPSK	406
7.7	Minimum Shift Keying	407
7.8	Quadrature Amplitude Modulation (QAM)	411
7.8.1	Types of QAM	411
7.9	Bandwidth Efficiency	414
7.9.1	Comparison of Modulation Methods	415
7.9.2	Effects of Going Through the Origin	415
7.10	Digital Modulation Types	416
7.10.1	<i>I/Q</i> Offset Modulation	416
7.10.2	Differential Modulation	417
7.10.3	Constant-Amplitude Modulation	418
7.11	Spectral Efficiency Versus Power Consumption	419
7.12	Time and Frequency Domain View of Digitally Modulated Signal	419
7.12.1	Power and Frequency View	420
7.13	Digital Transmitters and Receivers	421
7.13.1	Digital Receiver	421



<b>8. Information Theory</b>	<b>431</b>
8.1 Introduction	431
8.2 Measure of Information	432
8.3 Joint and Conditional Entropy	434
8.3.1 Joint Entropy	434
8.3.2 Conditional Entropy	435
8.3.3 Entropy Rate	435
8.3.4 Mutual Information	436
8.4 Differential Entropy	436
8.4.1 Information Rate	437
8.4.2 Source Coding to Increase Average Information per Bit	438
8.5 The Source Coding Theorem	438
8.5.1 Source Coding Algorithm	441
8.6 Data Compaction	441
8.7 Prefix Coding	442
8.8 Shannon–Fano Coding	445
8.9 The Huffman Source Coding Algorithm	446
8.9.1 Huffman Coding Algorithm	446
8.10 Lempel–Ziv Source Coding Algorithm	448
8.11 Capacity of Gaussian Channel	451
8.11.1 Bandwidth $S/N$ Trade-off	453
8.12 Discrete Memoryless Channel	454
8.13 Modelling of Communication Channels	456
8.14 Channel Capacity	457
8.15 Noisy Channel Coding Theorem	460
8.16 Gaussian Channel Capacity	460
8.17 Bounds on Communication	463
8.18 Information Capacity of Coloured Noisy Channel	465
8.19 Rate Distortion Theory	468
8.19.1 Rate Distortion Function	469
8.20 Data Compression	470
8.21 Automatic Repeat Request	471
8.21.1 Stop and Wait System	472
8.21.2 Continuous ARQ with Pull Back	472
8.21.3 Continuous ARQ with Selective Repeat	472
8.21.4 Performance of ARQ Systems	473
8.21.5 Throughput	474
8.22 Error-Free Communication over Noisy Channel	476
8.23 Channel Capacity of Continuous Channel	479
8.24 An Optimum Modulation System: An Application of Information Theory	480
8.24.1 A Comparison of AM System with an Optimum System	482
8.24.2 Comparison of FM Systems	484
8.24.3 Comparison of PCM and FM	485

<b>9. Introduction to Probability, Random Variable, and Random Processes</b>	<b>495</b>
9.1 Introduction to Probability	495
9.1.1 The Classical Approach	496
9.1.2 The Relative Frequency Approach	496
9.1.3 The Axiomatic Approach	496
9.2 Elementary Set Theory	497
9.3 The Axiomatic Approach	498
9.3.1 Implications of the Axioms of Probability	500
9.4 Conditional Probability	500
9.4.1 Total Probability Theorem: Discrete Version	501
9.4.2 Bayes' Theorem	502
9.4.3 Independence	503
9.5 Random Variable	504
9.5.1 Discrete Random Variable	504
9.5.2 Cumulative Distribution Function (CDF)	504
9.5.3 Types of Random Variables	505
9.5.4 Functions of a Random Variable	508
9.5.5 Statistical Averages	509
9.5.6 Multiple Random Variables	510
9.5.7 Multiple Functions of Multiple Random Variables	510
9.5.8 Sums of Random Variables	511
9.5.9 Jointly Gaussian Random Variables	511
9.6 Random Process	512
9.6.1 Continuous and Discrete Random Processes	513
9.6.2 Distribution and Density Functions	514
9.6.3 Stationary Random Process	514
9.6.4 Multiple Random Processes	516
9.6.5 Bandpass Random Process	516
9.6.6 Gaussian Random Process	517
9.6.7 Random Process Through a Linear Time Invariant System	517
9.6.8 Statistical Averages	519
9.6.9 Power Spectral Density of Stationary Processes	519
9.6.10 Power Spectra in LTI System	519
9.6.11 Power Spectral Density of a Sum Process	520
9.7 Gaussian Process	520
9.7.1 Central Limit Theorem	522
9.7.2 Properties of Gaussian Process	522
<i>Appendix A MATLAB Exercises</i>	529
<i>Appendix B Important Mathematical Relations/Formulae</i>	537
<i>Appendix C Fourier Series Representation and Its Properties</i>	543
<i>Appendix D Miscellaneous</i>	546
<i>Index</i>	552

# Introduction

## 1.1 WHAT IS COMMUNICATION?

It is the study of the fundamental concept and principles of transferring information from one place to another. This involves the process of transmission, reception, and processing of information between locations. The source can be in a continuous form as in the case of analog signals or in a digital form.

As in the case of discrete signals, all forms of information, however, should be converted into an electrical signal before being sent via some medium. The medium can be a wire, a coaxial cable, a waveguide, an optical fibre, or atmosphere as in the case of radio and TV broadcasting. The medium is sometimes called a channel.

The first communication system was telegraphy followed by telephony and then the wireless system, which was used to broadcast radio programmes.

Invention of transistors and later integrated circuits, LSI, and VLSI has made the design and development of low-power, small-size, lightweight, high-speed, and reliable communication systems possible. Introduction of fibre optic cable as a medium resulted in providing an extremely high bandwidth and making possible transmission of voice, data, and picture over the same channel. The world is witnessing a significant growth in the field of communication in the form of cellular or mobile phones and high-speed communication networks with the help of powerful and faster computers. Today the world has become smaller, thanks to the modern advancement in communication engineering.

Initial communication systems were analog but present-day communication systems are mostly digital.

## 1.2 MODULATION AND ITS TYPES

The original information is mostly not in the form that is suitable for transmission. If the distance is quite small, this problem never arises. In this case, we call the transmission as baseband transmission. However, for a long distance, original information has to be transformed into some other form so that it is most suitable for transmission. The process of impressing such information onto a high-frequency component, called carrier, is known as *modulation*.

### 1.2.1 Need for Modulation

Suppose you are on the 36th floor of a building and your friend is standing down on the ground floor. Now you want to convey some information to him. (Assume that no mobile phone is available with you or him.) If you write this information on a piece of paper and drop it down to him through the balcony or window, chances are that it may not reach him. This is due to the fact that this piece of paper containing the information is so light that it will float in the air and drift away and will never reach your friend. To ensure that the message reaches him, just wrap this piece of paper around a small stone and drop it. Due to the weight of the stone and the gravity, the stone just drops down straight and your friend can pick it up. He takes the piece of paper containing the information and throws the stone. Precisely the same method is followed when we transmit a signal over a long distance. The original low-frequency signal is impressed onto a high-frequency signal called carrier (since this carries the low-frequency information) and transmitted over a long distance. On the receiver end, this signal is received and the carrier is removed and discarded and the low-frequency signal containing the information is retained.

We can summarize the need for modulation as follows.

- To translate the frequency of a low-pass signal to a higher band so that the spectrum of the transmitted bandpass signal matches the bandpass characteristics of the channel.
- For efficient transmission, it has been found that the antenna dimension has to be of the same order of magnitude as the wavelength of the signal being transmitted. Since  $C = \lambda f$  for a typical low-frequency signal of 2 kHz, the wavelength works out to be 150 km. Even assuming the height of the antenna half the wavelength, the height works out to be 75 km, which is impracticable.
- To enable transmission of a signal from several message sources simultaneously through a single channel employing frequency division multiplexing.
- To improve noise and interference immunity in transmission over a noise channel by expanding the bandwidth of the transmitted signal.

### 1.2.2 Frequency Translation

We have seen that the modulation process shifts the modulating frequency to a higher frequency, which in turn depends on the carrier frequency, thus producing upper and lower sidebands. Hence, signals are upconverted from low frequencies to high frequencies and downconverted from high frequencies to low frequencies in the receiver. The process of converting a frequency or a band of frequencies to another location in the frequency spectrum is called *frequency translation*.

### 1.2.3 Types of Modulation

Depending on whether the amplitude, frequency, or phase of the carrier is varied in accordance with the modulation signal, we classify the modulation as amplitude modulation, frequency modulation, or phase modulation. The method of converting information into pulse form and then transmitting it over a long distance is called *pulse modulation*.

### 1.3 TRANSMITTER

The message as it arrives may not be suitable for direct transmission. It may be voice signal, music, picture, or data. The signals, which are not of electrical nature, have to be converted into electrical signals. Hence the need for transducer arises. Examples are microphone for speech and camera for pictures. The electrical signals thus generated are called modulating signals. These signals modulate a carrier and this modulated carrier is transmitted. The type of modulation depends on systems. They may be of high level or low level. They can also be any variation or a combination of these. Figure 1.1 shows a typical transmitter.

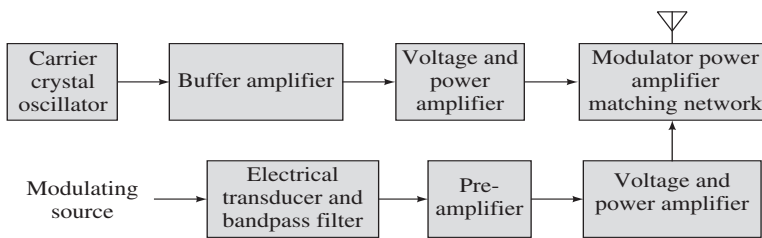


Fig. 1.1 Block diagram of a typical transmitter

The information to be transmitted comes out as an electrical signal from the transducer. This signal is bandlimited through a bandpass filter and is connected to a preamplifier, then to a voltage and power amplifier and finally is given as one of the inputs to the modulator. The other input to the modulator is the carrier, which is generated normally from a crystal oscillator and is then connected to a buffer amplifier and a voltage and power amplifier before connecting to the modulating input. The output of the modulator is connected to a power amplifier and this signal is coupled to the antenna through a matching network to avoid reflection, etc. The power of the transmitter depends on the range of the transmission.

### 1.4 RECEIVER

Many types of receivers are available in communication systems. A typical receiver is shown in Fig. 1.2. The type of receiver depends on the type of modulation, carrier frequency, the strength of signal received, etc. Most of the modern-day receivers are of superheterodyne type. The received signal from the antenna is fed to an RF amplifier and is given as one of the inputs to a mixer. The other input is the local oscillator, which can be tuned to different frequencies. The output of the mixer is the intermediate frequency, which is fixed irrespective of the frequency of the received signal. This is fed to an intermediate frequency amplifier and to a demodulator. The detector output is given to an audio/video amplifier depending on the original information and is fed to a loudspeaker or a video display unit as the case may be.

## 4 Analog Communication

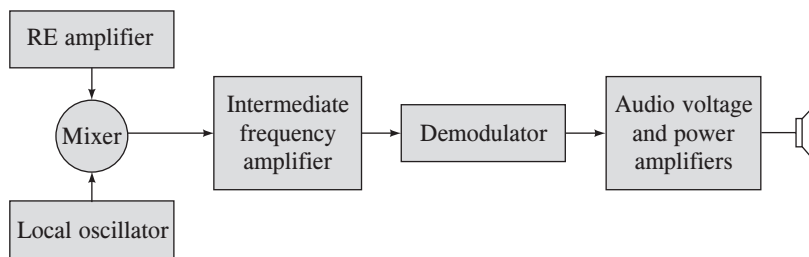


Fig. 1.2 Block diagram of a typical receiver

### 1.5 DIGITAL COMMUNICATION SYSTEM

So far, we have described the electrical communication system in rather a broad sense on the assumption that the message signal is a continuous time varying waveform. Such waveform is called *analog signal*. These signals can be transmitted over the communication channel by modulating a carrier that is demodulated at the receiver end. Such a communication system is called an *analog communication system*.

An analog source may be converted into a digital form and this message can be transmitted as digital data. At the receiver, these digital data are converted back into analog signals. There are numerous advantages with this type of transmission. Signal fidelity is better controlled. Digital transmission allows us to regenerate the digital signal in long-distance transmission, thus eliminating the effects of noise at each regeneration point. But in the case of an analog transmission, the noise added is amplified along with the signal. Another advantage in digital transmission is removal of redundancy, which is inherent in analog systems. In digital systems, redundancy is removed prior to the modulation, which results in conserving bandwidth. They are also cheaper to implement. Figure 1.3 gives the block diagram of a basic digital communication system transmitter.

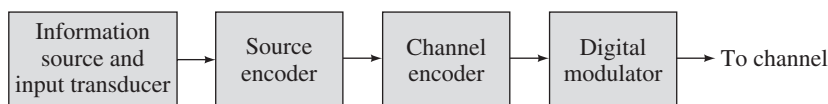
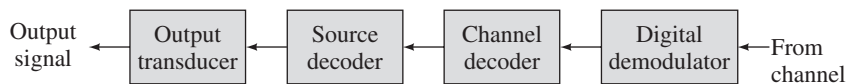


Fig. 1.3 Block diagram of a digital communication transmitter

The analog input is converted into a sequence of binary digits by a source encoder, which is generally an analog-to-digital converter. We normally represent the message signal with as few binary digits as possible. This helps obtain the output with little or no redundancy. The process of efficiently converting the output of either an analog or a digital source into a sequence of binary digits is called *source encoding* or *data compression*. The source encoded outputs, which are a sequence of binary digits, are called *information sequence*. This is passed on to the channel encoder. The channel encoder is introduced in a controlled manner. Some redundancy in the binary information sequence can be used at the receiver to overcome the effects of noise and interference encountered in the transmission of signal through the channel. Thus, the added redundancy serves

to increase the reliability of the received data and improves the fidelity of the received signal. The redundancy in the information sequence aids the receiver in decoding the desired information sequence. The binary sequence at the output of the channel encoder is passed through the digital modulator, which serves as the interface to the communication channel.

At the receiving end, the digital demodulator processes the received waveform and passes it onto a channel decoder. The channel decoder output is connected to the source decoder, which is generally a digital-to-analog converter, and the original analog signal is obtained. Figure 1.4 gives the receiver block diagram.



**Fig. 1.4** Block diagram of a digital communication receiver

It has to be kept in mind that in all communication systems, the transmitter and receiver must be in agreement with the modulation method used.

## 1.6 MULTIPLEXING OF SIGNALS

When it is required to transmit more signals on the same channel, baseband transmission fails, as in the case of audio signals being broadcast from different stations on the same channel. The reason for this is the interference between each audio signal due to their frequencies being more or less the same. To avoid this, either frequency division multiplexing or time division multiplexing is employed.

### 1.6.1 Frequency Division Multiplexing

In this method, various carrier frequencies, which are quite apart, are chosen and these carriers get modulated by different baseband signals. Thus, the modulated carriers are transmitted over the same channel. At the receiver, tunable bandpass filters are used to separate each modulated carrier and then demodulate it to recover the baseband signal. This method of transmitting several channels simultaneously is known as *frequency division multiplexing* (FDM).

Here the bandwidth of the channel is shared by various signals without any overlapping.

### 1.6.2 Time Division Multiplexing

In this method, several signals are transmitted over a time interval. Each signal is allotted a time slot and it gets repeated cyclically. The only difference compared to FDM is that the signals are to be sampled before sending. Hence, the signals will be in the form of pulse trains. At the receiver, there will be a synchronizer to recover each signal.